

Improved Oniscus Granulatus Algorithm for solving optimal reactive power problem

Kanagasabai Lenin

Department of EEE, Prasad V. Potluri Siddhartha Institute of Technology, Kanuru, Vijayawada, Andhra Pradesh 520007, India

Corresponding Author Email: gklenin@gmail.com

Received: April 9 2018

Accepted: June 12 2018

Keywords:

optimal reactive power, Oniscus Granulatus Algorithm, transmission loss

ABSTRACT

In this paper, an Improved Oniscus Granulatus Algorithm (IOSA) is proposed to solve optimal reactive power problem. The behaviour of Oniscus Granulatus has been imitated to formulate the proposed algorithm. Exploration & Exploitation has been amplified in proposed Improved Oniscus Granulatus Algorithm (IOSA). IOSA has been tested on standard IEEE 30 bus test system and simulation results show clearly the good performance of the proposed algorithm in reducing the real power loss and voltage variables are within the limits.

1. INTRODUCTION

Main objective of optimal reactive power problem is to minimize the real power loss and bus voltage deviation. Different conventional techniques [1-8] have been already implemented to solve the optimal reactive power problem. Due to the difficulty in managing inequality constraints many algorithm fail to reach the global solution. Recently many types of Evolutionary algorithms have been used to solve optimal reactive power flow problem [9-11], & some algorithms good in exploration & some better in exploitation alone. Proposed algorithm equally balances the exploration & exploitation in the search of global solution in optimal reactive power problem. In this paper, an Improved Oniscus Granulatus Algorithm (IOSA) is proposed for solving optimal reactive power problem. IOSA is inspired by the behaviour of Oniscus Granulatus. In standard IEEE 30 bus test system proposed Improved Oniscus Granulatus Algorithm (IOSA) has been tested and simulation results show the excellent performance of the IOSA in reducing the real power loss and voltage variables are within the specified limits.

2. PROBLEM FORMULATION

2.1 Active power loss

Key objective is to minimize the active power loss in the transmission network & described as,

$$F = PL = \sum_{k \in Nbr} g_k (V_i^2 + V_j^2 - 2V_i V_j \cos \theta_{ij}) \quad (1)$$

where g_k : is the conductance of branch between nodes i and j , Nbr : is the total number of transmission lines in power systems. P_d : is the total active power demand, P_{gi} : is the generator active power of unit i , and P_{gslack} : is the generator active power of slack bus.

2.2 Voltage profile improvement

In order to minimize the voltage deviation, the above

equation is rewritten as,

$$F = PL + \omega_v \times VD \quad (2)$$

where ω_v : is a weighting factor of voltage deviation.

Voltage deviation (VD) is calculated by,

$$VD = \sum_{i=1}^{Npq} |V_i - 1| \quad (3)$$

2.3 Equality constraint

In equality constraint Power balance equation represented by,

$$P_G = P_D + P_L \quad (4)$$

2.4 Inequality constraints

Limits on components (slack bus, and reactive power of generators) in power system are given by the inequality constraints.

$$P_{gslack}^{min} \leq P_{gslack} \leq P_{gslack}^{max} \quad (5)$$

$$Q_{gi}^{min} \leq Q_{gi} \leq Q_{gi}^{max}, i \in N_g \quad (6)$$

$$V_i^{min} \leq V_i \leq V_i^{max}, i \in N \quad (7)$$

$$T_i^{min} \leq T_i \leq T_i^{max}, i \in N_T \quad (8)$$

$$Q_c^{min} \leq Q_c \leq Q_c^{max}, i \in N_c \quad (9)$$

where N is the total number of buses, N_T is the total number of Transformers; N_c is the total number of shunt reactive compensators [22].

3. ONISCUS GRANULATUS ALGORITHM

Oniscus Granulatus algorithm (OGA) is inspired by the behaviour of Oniscus Granulatus & it is a species of woodlice

[21]. Normally Oniscus Granulatus live in groups, seen in moist, dark & cool places. But they can also survive in extremely harsh environment. When they sense by sensory receptors in the body about the surroundings conditions if it is not favourable for their living then they will move on to find a good place for their living.

The most important formula of the OGA approach is given by,

$$y_i^{k+1} = y_i^k - (1 - \lambda) \left(y_i^k - \arg \min_{y_i^k} \{f(y_j^k)\} \right) + \lambda Q \tau \quad (10)$$

where $\lambda \in (0, 1)$, τ is a vector & each element being an arbitrary number.

Where Q is defined as,

$$Q = \frac{f(y_i^k + \tau) - \min(f(y_i^k + \tau))}{\max(f(y_i^k + \tau)) - \min(f(y_i^k + \tau))}$$

Objective function $f(y)$, $y = [y_1, y_2, \dots, y_d]^T$

Generate initial position of Oniscus Granulatus y_i^0 ($i = 1, 2, \dots, N$)

Surrounding condition S_y at position y is determined by $f(y)$

For decision based on aggregation set weighted parameter λ

F^* has been initialized to an exceptionally large value

Each element of vector $y^* \in R^d$ has been initialized to an arbitrary value

While $k < \text{Maximum}$; step do

With the best surrounding condition, position will be obtained i.e., $y_b = \arg \min_{y_i^k} \{f(y_j^k)\}$ at the existing time in the midst of

the group of Oniscus Granulatus

If $\min_{y_i^k} \{f(y_j^k)\} < F^*$ then

$y^* = y_b$

$F^* = \min_{y_i^k} \{f(y_j^k)\}$ end if

Direction has been chosen arbitrarily $\tau = [\tau_1, \tau_2, \dots, \tau_d]^T$ to identify.

Spot the most excellent surrounding condition $\min \{S_y\}$ & most awful surrounding condition $\max \{S_y\}$ at position $y_i^k + \tau$ for $i = 1 : N$ all N Oniscus Granulatus ; for $i = 1 : N$ all N Oniscus Granulatus do

With respect to the position decide the difference as collective i.e., $y_i^k - \arg \min_{y_i^k} \{f(y_j^k)\}$

Exploration has to be identified (pr) & it has to be shift to a new-fangled position

Output y^* and the analogous function value F^*

4. IMPROVED ONISCUS GRANULATUS ALGORITHM

In the improved Oniscus Granulatus Algorithm $og_i(y) \leq 0$ ($j = 1, 2, \dots, m$) is introduced into the function. Penalty methodology has been utilized, and a new-fangled function will be acquired as below,

$$\check{f}(y) = f(y) + \gamma \sum_{i=1}^m og_i^2(y) h(og_i(y)) \quad (11)$$

where $h(og_i(y))$ is defined as,

$$h(og_i(y)) = \begin{cases} 1, & \text{if } og_i(y) > 0 \\ 0, & \text{if } og_i(y) \leq 0 \end{cases}, \gamma \gg 1 \text{ is penalty parameter.}$$

The expression $\gamma \sum_{i=1}^m og_i^2(y) h(og_i(y))$ takes a foremost role in the function. When $og_i(y) \leq 0$ ($i = 1, 2, \dots, m$) is fulfilled, then $h(og_i(y)) = 0, \forall i$, thus $\check{f}(y) = f(y)$.

$l_j \leq y_j \leq u_j$ with $j = 1, 2, \dots, d$, for simple bounds are hold by two system. The preliminary position of each Oniscus Granulatus is initially set, to convince the simple bounds, by the following equation:

$$y_{i,j}^0 = l_j + (u_j - l_j) \times \text{random}(0,1) \quad (12)$$

where $y_{i,j}^0$ denote the preliminary value of the j th variable of the position vector of the i th ($i = 1, 2, \dots, N$) Oniscus Granulatus; $\text{random}(0, 1)$ indicate an arbitrary number in the region $(0, 1)$.

The customized evolution rule is projected as follows:

$$y_i^{k+1} = Q_\Omega \left(y_i^k - (1 - \lambda) \left(y_i^k - \arg \min_{y_i^k} \{f(y_j^k)\} \right) \right) + \lambda Q \tau \quad (13)$$

Algorithm for the assessment of $Q_\Omega(y)$ with $y = [y_1, y_2, \dots, y_d]^T$

For $i = 1 : d$ do

If $y_i < l_i$ then

$y_i = l_i$

End if

If $y_i > u_i$ then

$y_i = u_i$

End if

End for

Return $y = [y_1, y_2, \dots, y_d]^T$

Improved Oniscus Granulatus Algorithm (IPSA) for solving reactive power problem

Cost function $f(y)$, $y = [y_1, y_2, \dots, y_d]^T$

Generate initial position of Oniscus Granulatus y_i^0 ($i = 1, 2, \dots, N$)

Surrounding condition S_y at position y is determined by $f(y)$

For decision based on aggregation set weighted parameter λ

F^* has been initialized to an exceptionally large value

Each element of vector $y^* \in R^d$ has been initialized to an arbitrary value

While $k < \text{Maximum}$ step do

With the best surrounding condition, position will be obtained i.e., $y_b = \arg \min_{y_i^k} \{f(y_j^k)\}$ at the existing time in the midst of

the group of Oniscus Granulatus

If $\min_{y_i^k} \{f(y_j^k)\} < F^*$ then

$y^* = y_b$

$F^* = \min_{y_i^k} \{f(y_j^k)\}$ end if

Direction has been chosen arbitrarily $\tau = [\tau_1, \tau_2, \dots, \tau_d]^T$ to identify.

Identify the most excellent surrounding condition $\min \{S_y\}$ & most awful surrounding condition $\max \{S_y\}$ at position $y_i^k + \tau$ for $i = 1 : N$ all N Oniscus Granulatus ; for $i = 1 : N$ all N Oniscus Granulatus do

With respect to the position decide the difference as collective i.e., $y_i^k - \arg \min_{y_i^k} \{f(y_j^k)\}$

Exploration has to be identified (pr) & shift to a new-fangled position

Shift to a new-fangled position & where $Q\Omega(y)$ has to be evaluated
 End for
 End while
 Output y^* and the analogous function value F^*

5. SIMULATION RESULTS

Validity of proposed Improved Oniscus Granulatus Algorithm (IOSA) has been verified by testing it in standard IEEE 30-bus, which has 41 branches, 6 generator-buses, 4 transformer-tap settings, 2shunt reactive compensators. Bus 1 is considered as slack bus. 2, 5, 8, 11 and 13 are taken as PV

buses & remaining as PQ buses. Control variables limits are given in Table 1.

Table 1. Key variable limits (Pu)

List of Variables	Minimum	Maximum	Type
Generator Bus	0.950	1.10	Continuous
Load Bus	0.950	1.050	Continuous
Transformer-Tap	0.90	1.10	Discrete
Shunt Reactive Compensator	-0.110	0.310	Discrete

In Table 2 Generators power limits are listed.

Table 2. Generators power limits

Bus	Pg	Pgminimum	Pgmaximum	Qgminimum	Qgmaximum
1	96.000	49.000	200.000	0.000	10.000
2	79.000	18.000	79.000	-40.000	50.000
5	49.000	14.000	49.000	-40.000	40.000
8	21.000	11.000	31.000	-10.000	40.000
11	21.000	11.000	28.000	-6.000	24.000
13	21.000	11.000	39.000	-6.000	24.000

Table 3. Control variables values after optimization

List of Control Variables	IOSA
V1	1.041900
V2	1.041000
V5	1.020600
V8	1.031000
V11	1.070400
V13	1.050000
T4,12	0.0000
T6,9	0.0000
T6,10	0.9000
T28,27	0.9000
Q10	0.1000
Q24	0.1000
Real power loss (MW)	4.2348
Voltage deviation	0.9089

Table 3 gives the control variables obtained after optimization. Table 4 presents the performance of the proposed IOSA. Table 5 list out the overall comparison of real power loss.

6. CONCLUSION

In this paper, an Improved Oniscus Granulatus Algorithm (IOSA) is successfully solved optimal reactive power problem. IOSA approach is inspired by the behaviour of Oniscus Granulatus. Potential of exploration & exploitation has been amplified by the Improved Oniscus Granulatus Algorithm (IOSA). Proposed IOSA has been tested on standard IEEE 30 bus test system and simulation results show clearly the good performance of the proposed algorithm in reducing the real power loss and voltage variables are within the limits.

Table 4. Narration of projected IOSA algorithm

No. of Iterations	28
Time taken	7.74
Real power loss (MW)	4.2348

Table 5. Evaluation of outcome

List of Techniques	Real power loss (MW)
SGA [23]	4.98
PSO [24]	4.9262
LP [25]	5.988
EP [25]	4.963
CGA [25]	4.980
AGA [25]	4.926
CLPSO [25]	4.7208
HSA [26]	4.7624
BB-BC [27]	4.690
MCS [28]	4.87231
Proposed IOSA	4.2348

REFERENCES

- [1] Alsac O, Scott B. (1973). Optimal load flow with steady state security. IEEE Transaction. PAS -1973, 745-751.
- [2] Lee KY, Paru YM, Ortiz JL. (1985). A united approach to optimal real and reactive power dispatch. IEEE Transactions on Power Apparatus and Systems PAS-104, 1147-1153
- [3] Monticelli A, Pereira MVF, Granville S. (1987). Security constrained optimal power flow with post contingency corrective rescheduling. IEEE Transactions on Power Systems: PWRS-2 (1): 175-182.
- [4] Deeb N, Shahidehpur SM. (1990). Linear reactive power optimization in a large power network using the decomposition approach. IEEE Transactions on Power System 5(2): 428-435.

- [5] Hobson E. (1980). Network constrained reactive power control using linear programming. *IEEE Transactions on Power Systems* PAS 99(4): 868-877.
- [6] Lee KY, Park YM, Oritz JL. (1993). Fuel –cost optimization for both real and reactive power dispatches. *IEE Proc.* 131C(3): 85-93.
- [7] Mangoli MK, Lee KY. (1993). Optimal real and reactive power control using linear programming. *Electr. Power Syst. Re.* 26: 1-10.
- [8] Canizares CA, de Souza ACZ, Quintana VH. (1996). Comparison of performance indices for detection of proximity to voltage collapse. *IEEE Transactions on Power Systems* 11(3): 1441-1450.
- [9] Anburaja K. (2002). Optimal power flow using refined genetic algorithm. *Electr. Power Compon. Syst.* 30: 1055-1063.
- [10] Devaraj D, Yeganarayana B. (2005). Genetic algorithm based optimal power flow for security enhancement. *IEE proc-Generation, Transmission and Distribution* 152(6): 899-905.
- [11] Berizzi A, Bovo C, Merlo M, Delfanti M. (2012). A ga approach to compare orpf objective functions including secondary voltage regulation. *Electric Power Systems Research* 84(1): 187–194.
- [12] Yang CF, Lai GG, Lee CH, Su CT, Chang GW. (2012). Optimal setting of reactive compensation devices with an improved voltage stability index for voltage stability enhancement. *International Journal of Electrical Power and Energy Systems* 37(1): 50–57.
- [13] Roy P, Ghoshal S, Thakur S. (2012). Optimal var control for improvements in voltage profiles and for real power loss minimization using biogeography based optimization. *International Journal of Electrical Power and Energy Systems* 43(1): 830–838.
- [14] Venkatesh B, Sadasivam G, Khan M. (2000). A new optimal reactive power scheduling method for loss minimization and voltage stability margin maximization using successive multi-objective fuzzy lp technique. *IEEE Transactions on Power Systems* 15(2): 844–851.
- [15] Yan W, Lu S, Yu D. (2004). A novel optimal reactive power dispatch method based on an improved hybrid evolutionary programming technique. *IEEE Transactions on Power Systems* 19(2): 913–918.
- [16] Yan W, Liu F, Chung C, Wong K. (2006). A hybrid genetic algorithm interior point method for optimal reactive power flow. *IEEE Transactions on Power Systems* 21(3): 1163-1169.
- [17] Yu J, Yan W, Li W, Chung C, Wong K. (2008). An unfixed piecewise optimal reactive power-flow model and its algorithm for ac-dc systems. *IEEE Transactions on Power Systems* 23(1): 170-176.
- [18] Capitanescu F. (2011). Assessing reactive power reserves with respect to operating constraints and voltage stability. *IEEE Transactions on Power Systems* 26(4): 2224–2234.
<http://dx.doi.org/10.1109/TPWRS.2011.2109741>
- [19] Hu Z, Wang X, Taylor G. (2010). Stochastic optimal reactive power dispatch: Formulation and solution method. *International Journal of Electrical Power and Energy Systems* 32(6): 615–621.
<http://dx.doi.org/10.1016/j.ijepes.2009.11.018>
- [20] Kargarian A, Raoofat M, Mohammadi M. (2012). Probabilistic reactive power procurement in hybrid electricity markets with uncertain loads. *Electric Power Systems Research* 82(1): 68–80.
<http://dx.doi.org/10.1016/j.epsr.2011.08.019>
- [21] Zhang Y, Li S. (2017). PSA: A novel optimization algorithm based on survival rules of porcellio scaber. Available at <https://arxiv.org/abs/1709.09840>.
- [22] Zhou J, Tang BG, Ren XW. (2017). Research on prediction model for icing thickness of transmission lines based on bp neural network optimized with improved fruit fly algorithm. *AMSE Journals-AMSE IETA Publication Series: Advances* 60(1): 255-269.
- [23] Wu.QH, Cao YJ, Wen JY. (1998). Optimal reactive power dispatch using an adaptive genetic algorithm. *Int. J. Elect. Power Energy Syst.* 20: 563-569.
[http://dx.doi.org/10.1016/S0142-0615\(98\)00016-7](http://dx.doi.org/10.1016/S0142-0615(98)00016-7)
- [24] Zhao B, Guo CX, Cao YJ. (2005). Multiagent-based particle swarm optimization approach for optimal reactive power dispatch. *IEEE Trans. Power Syst.* 20(2): 1070-1078.
<http://dx.doi.org/10.1109/TPWRS.2005.846064>
- [25] Mahadevan K, Kannan PS. (2010). Comprehensive learning particle swarm optimization for reactive power dispatch. *Applied Soft Computing* 10(2): 641–52.
<http://dx.doi.org/10.1016/j.asoc.2009.08.038>
- [26] Khazali AH, Kalantar M. (2011). Optimal reactive power dispatch based on harmony search algorithm. *Electrical Power and Energy Systems* 33(3): 684–692.
<http://dx.doi.org/10.1016/j.ijepes.2010.11.018>
- [27] Sakthivel S, Gayathri M, Manimozhi V. (2013). A Nature inspired optimization algorithm for reactive power control in a power system. *International Journal of Recent Technology and Engineering* 2(1): 29-33.
- [28] Sharma T, Srivastava L, Dixit S. (2016). Modified cuckoo search algorithm for optimal reactive power dispatch. *Proceedings of 38 th IRF International Conference*, pp. 4-8.